



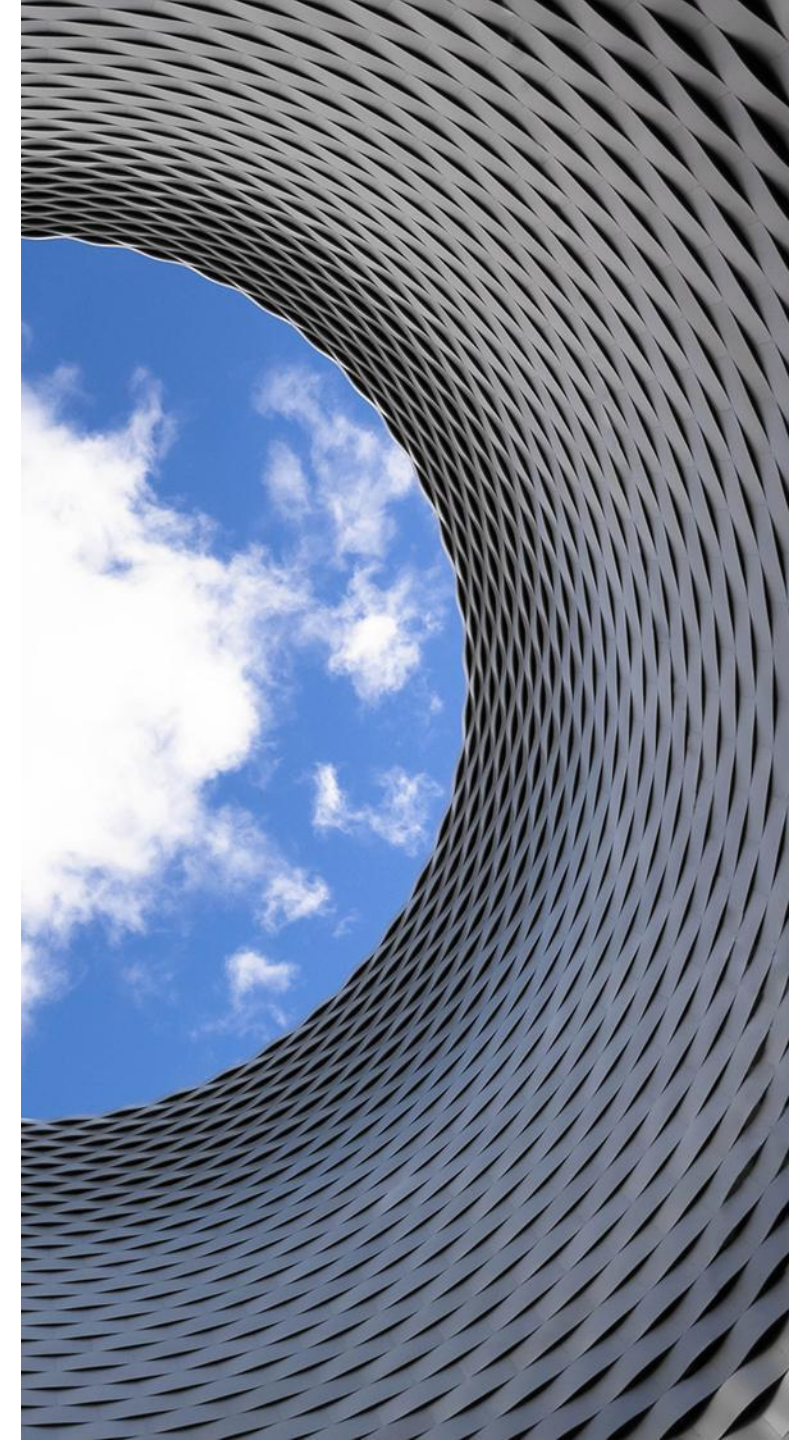
Beyond operator()

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How to make something callable?



Restrictions of operator()

- You're working on an object of a class type
- You own the class
- The action to “call” the object needs to have an unambiguous meaning

- Java ~~operator()~~
- C# ~~operator()~~
- Rust ~~operator()~~

```
interface Runnable {  
    void run();  
}
```

```
class MyThread implements Runnable {  
    public void run() {  
        // code to execute  
    }  
}
```

```
void addToPool(Runnable obj) { /* */ }
```

...

```
exec.addToPool(new MyThread());
```

Java with lambda

```
interface Runnable {  
    void run();  
}
```

```
void addToPool(Runnable obj) { /* */ }
```

```
...
```

```
exec.addToPool(() -> { /* code to execute */ });
```

Restrictions of operator()

- You're working on an object of a class type
- You own the class
- ~~• The action to "call" the object needs to have an unambiguous meaning~~



```
delegate int GetCount();
```

```
static void PrintCount(GetCount f)  
{  
    int i = f();  
    System.Console.WriteLine("{0}", i);  
}
```

```
string s = "The quick brown fox jumped over the lazy dog.";  
PrintCount();
```


C# extension methods + delegates



```
public static class StringExtension
{
    public static int WordCount(this string str)
    {
        return /* impl code */;
    }
}
```

```
string s = "The quick brown fox jumped over the lazy dog.";
PrintCount(s.WordCount);
```

Restrictions of operator()

- You're working on an object of a class type
- ~~• You own the class~~
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Rust



```
trait FnOnce<Args> {  
    type Output;  
    extern "rust-call" fn call_once(self, args: Args) -> Self::Output;  
}
```

Rust

```
struct MyArray([i32; 3]);

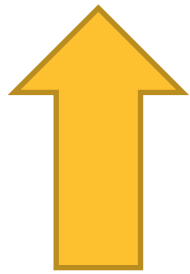
impl FnOnce<(usize,)> for MyArray {
    type Output = i32;
    extern "rust-call" fn call_once(self, (i,): (usize,)) -> i32 {
        let MyArray(arr) = self;
        return arr[i];
    }
}
```

Restrictions of operator()

- ~~• You're working on an object of a class type~~
- ~~• You own the class~~
- ~~• The action to "call" the object needs to have an unambiguous meaning~~



```
interface Runnable {  
    void run();  
}
```



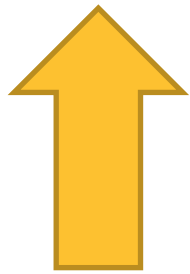
This is a type-erasure

```
delegate int GetCount();
```



This is a type-erasure

```
fn foo(f: Box<dyn FnOnce(usize) -> i32>);
```



This is a type-erasure

What's wrong with lambda, bind_front?



Example from the paper: lambda



```
pack.start([obj{std::move(obj)}]<class... T>(T &&...args) mutable
    { return obj.send(std::forward<T>(args)...); });
```

Example from the paper: bind_front



```
pack.start(std::bind_front(&Conn::send, std::move(obj)));
```

Example from the paper: proposed



```
pack.start({std::nontype<&Conn::send>, std::move(obj)});
```

Comments to address

Lambda can be made better

Bind_front can be made better

Constexpr argument can
replace the nontype tag

Lambda can be made better



// before

```
pack.start([obj{std::move(obj)}]<class... T>(T &&...args) mutable  
    { return obj.send(std::forward<T>(args)...); });
```

// suggested (handle the case where 'send' is an overload set)

```
pack.start([obj{std::move(obj)}](auto &&...args)  
    { return obj.send(>> args...); });
```

Response

- Bind_front stills has cleaner semantics compared to lambda in this use case
- Still complicates stacks in debug information
- Moved twice (the original comment assumed &obj)
- Overload set can be handled in a better way when evolving the language:

Discussed in the paper



```
// proposed (doesn't handle overload set)
pack.start({std::nontype<&Conn::send>, std::move(obj)});
```

```
// proposed + vector-of-bool's "expression lambda"
pack.start({std::nontype<[] [&1.send]>, std::move(obj)});
```

```
// proposed + p0834
pack.start({std::nontype<[].send>, std::move(obj)});
```


Bind_front can be made better



// before

```
pack.start(std::bind_front(&Conn::send, std::move(obj)));
```

// suggested

```
pack.start(std::bind_front(std::nontype<&Conn::send>, std::move(obj)));
```

Response

- Mental model is restricted to 'bind'
- Still complicates stacks in debug information
- Moved twice
- nontype isn't meant to be callable (more on that later)

Suggested in the paper



// before

```
pack.start(std::bind_front(&Conn::send, std::move(obj)));
```

// suggested

```
pack.start(std::bind_front<&Conn::send>(std::move(obj)));
```

Handle non-movable types

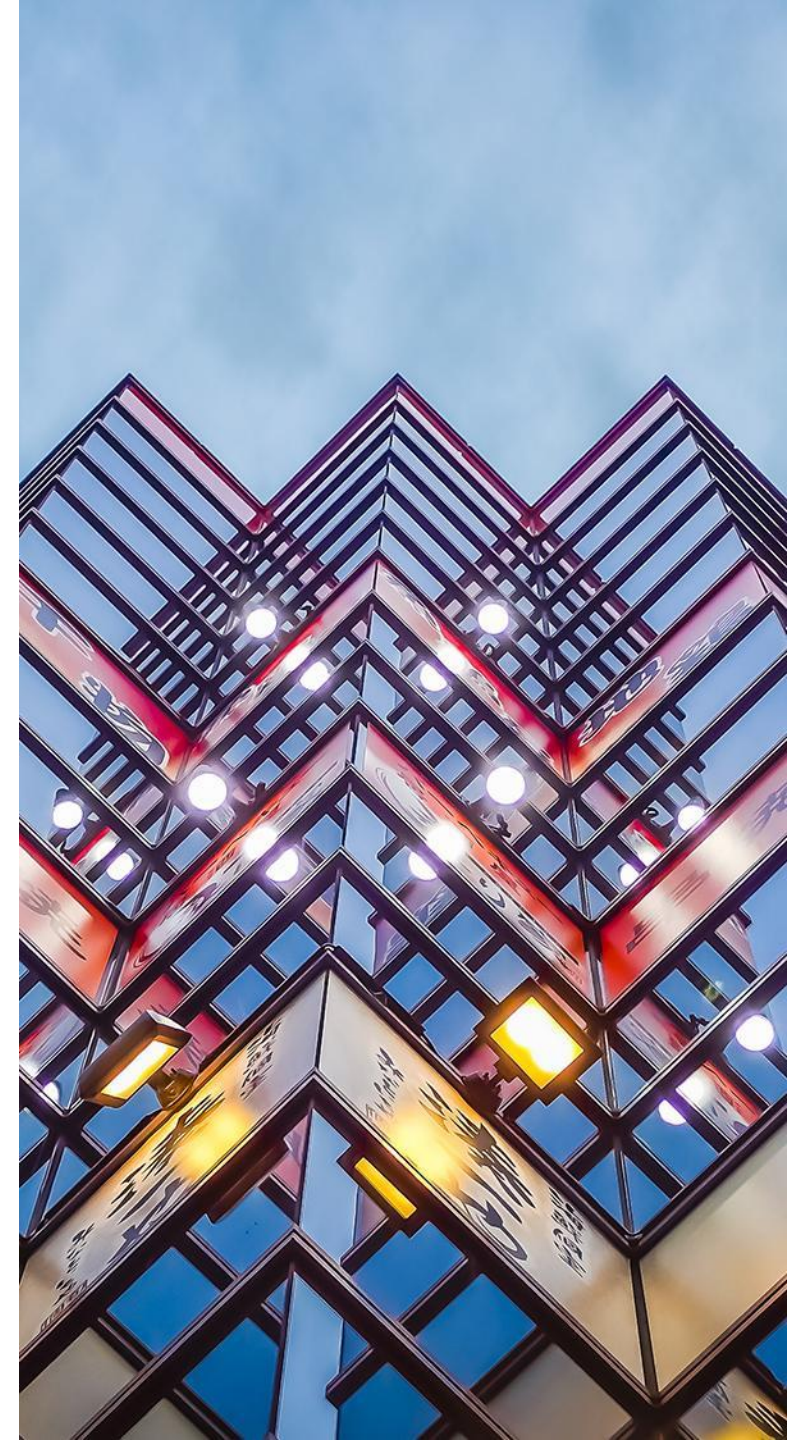
```
// wished
```

```
DB db("example.db", 100ms, true);  
q.emplace(std::nontype<&DB::connect>, std::move(db));
```

```
// solved
```

```
q.emplace(std::nontype<&DB::connect>,  
          std::in_place_type<DB>, "example.db", 100ms, true);
```

What's my mental model for this feature?



Example from last meeting



```
struct IDoWorkCallback
{
    virtual void OnEvent(WorkResult status, IData &object) = 0;
};

using IDoWorkCallbackPtr = std::shared_ptr<IDoWorkCallback>;

struct WorkContext
{
    void Add(IDoWorkCallbackPtr callback);
};
```



Example: proposed

```
struct WorkContext
{
    typedef void OnEvent(WorkResult status, IData &object);
    void Add(std::function<OnEvent> callback);

    void Add(IDoWorkCallbackPtr callback)
    {
        Add({std::nontype<&IDoWorkCallback::OnEvent>, callback});
    }
};
```

Proposed outcome

```
struct CMyReportingCallback : IDoWorkCallback
{
    void OnEvent(WorkResult status, IData &object) override;
};     Notify
```

```
CMyReportingCallback cb;
ctx.Add({std::nontype<&CMyReportingCallback::OnEvent>, cb});
                                           Notify
```


My mental model



```
struct CMyReportingCallback
{
    void Notify(WorkResult status, IData &object);
};
```

```
template<invocable<WorkResult, IData &> T>
void Accept(T f);
```

```
Accept(cb);
```

A form of concept adaptation

```
struct CMyReportingCallback
{
    void Notify(WorkResult status, IData &object);
};

concept_map invocable<CMyReportingCallback, WorkResult, IData &>
{
    using operator() = CMyReportingCallback::Notify;
};
```

Concept_map → impl block

```
trait Callable<Args> {  
    fn call(&self, args: Args);  
}
```

```
impl Callable<(WorkResult, IData)> for CMyReportingCallback {  
    fn call(&self, (status, object): (WorkResult, IData)) {  
        self.Notify(status, object);  
    }  
}
```

A one-time impl block

```
CMyReportingCallback cb;  
ctx.Add({std::nontype<  
    [](auto &cb, WorkResult status, IData &object)  
    {  
        LOG(INFO) << "status: " << status;  
        cb.Notify(status, object);  
    }>,  
cb});
```

An impl block

```
template<class T>
inline constexpr auto impl_invocable_for = std::nontype<void>;
template<>
inline constexpr auto impl_invocable_for<CMyReportingCallback> = std::nontype<
    [](auto &cb, WorkResult status, IData &object)
    {
        LOG(INFO) << "status: " << status;
        cb.Notify(status, object);
    }>;
...

ctx.Add({impl_invocable_for<CMyReportingCallback>, cb});
```

Nontype, or constexpr parameter



- `nontype<f>` is a single-entry witness table passed to a type-erasure at compile-time
- C++ makes switching between passing at runtime vs. at compile-time visible in the language via non-type template parameters
- However, you cannot pass template parameters solely to constructors
- The suggestion is as same as saying making the following equivalent

```
pack.start(std::bind_front(&Conn::send, std::move(obj)));  
// and  
pack.start(std::bind_front<&Conn::send>(std::move(obj)));
```



Thank you

